

Fundamentals For Control Of Robotic Manipulators

By Antti J. Koivo

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Basic Concepts of Robot control. Robot Control System Task The task of a robot control system is to execute the planned sequence of motions and forces in the presence

dblp: IEEE Transactions on Industrial Electronics, -

Redundancy resolution of robotic manipulators with neural computation. 230 Antti J. Koivo: Nonlinear predictive control with application to manipulator with

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To do this, criteria for "optimal" performance and ways to optimize design, structure, and control of robots must be developed and implemented.

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Analysis of Multifingered Hands. Jeffrey Kerr. General Motors Research Laboratories, Warren, Towards versatile legged robots through active impedance control;

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FUNDAMENTALS FOR CONTROL OF ROBOTIC MANIPULATORS -

Material Type: Book: Language: English: Title: FUNDAMENTALS FOR CONTROL OF ROBOTIC MANIPULATORS : Author(S) Antti J. Koivo : Publication Data: New York: John Wiley & Sons

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