

# **Using Robots In Hazardous Environments: Landmine Detection, De-mining And Other Applications**

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**Chapter 10 (in Part 2): Detecting Landmine Fields -**

Using Robots in Hazardous Environments: Landmine detection, de-mining and other applications p. 244-268. (2011) [Kapitel]

**Geert De Cubber | Mendeley -**

View Geert De Cubber's profile on Mendeley Geert s main task is to apply computer vision techniques to mobile robots, rendering these robots able to

### **Research and Markets: Using Robots in Hazardous -**

Research and Markets: Using Robots in Hazardous Environments: Landmine Detection, De-Mining and Other Applications is Essential for Those Researching the

### **Robotics Industry Insights - Chemical and -**

Among the many justifications for using robotics, the most important is to shield people from working in dangerous environments and from handling hazardous materials

### **Analysis of Robots for Hazardous Environments -**

use of robots for applications in hazardous and/or inaccessible environments such as those in which space exploration, Design of Robots for Hazardous Environments.

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### **What Are the Benefits of Using Robots? - Brighthub -**

Some of the advantages for using robots are of human labor due to the existence of hazardous environments. Robots can be used effectively in such

### **Robots for Hazardous Environments Group Server -**

The focus of the group is on the study of fault detection and fault tolerance for robot systems used in hazardous environments.

### **Gold Mining And The Environment - -**

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### **Verification of Behaviour Networks Using -**

Using robots in hazardous environments: Landmine detection, de-mining and other applications. Verification of Behaviour Networks Using Finite-State Automata

### **Using Robots in Hazardous Environments - Research -**

There have been major recent advances in robotic systems that can replace humans in undertaking hazardous activities in demanding or dangerous environments.

### **Fundamentals Of Fire Fighter Skills - -**

Using Robots in Hazardous Environments: Landmine Detection, De-mining and Other Applications. Yvan Baudoin, Maki K Habib

### **Start - Dr. sc. Ahmet SHALA -**

Ahmet Shala Universiteti i Prishtines Fakulteti i Inxhinierise Using robots in hazardous environments: Landmine detection, de-mining and other applications,

### **Robotics/Exotic Robots/ Hazardous Environment -**

The definition of hazardous is involving or exposing one to risk. Some examples of hazardous environments would be nuclear reactors, outside earth s atmosphere, and

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operated systems deployed in hazardous environments for and other heavy industrial applications, landmine clearance, hazardous materials handling

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Using robots in hazardous environments: Landmine detection, de-mining and other applications. Authored by Daniela Doroftei + 2. Daniela Doroftei. Geert De Cubber.

### **Mechanical mine clearance: Development, -**

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Mechanical mine clearance: Development, applicability and difficulties.

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### **BROKK Heavy-Duty Robots for IED and UXO -**

For more than 30 years, Brokk has been the leading supplier of remotely operated systems deployed in hazardous environments. With more than 5000 Brokk robots deployed

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